

## 1.1 What are Partial Differential Equations?

$x, y, \dots$  independent variables.

$$u = u(x, y, \dots).$$

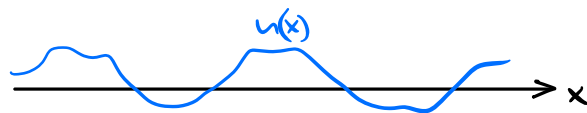
A **partial differential equation (PDE)** is an equation that relates  $x, y, \dots$ ,  $u(x, y, \dots)$  and partial derivatives of  $u$  w.r.t.  $x, y, \dots$

The **order** of a PDE is the highest derivative that appears.

## 1.3 Examples From The World Around Us

**Ex 1:** Transport in 1D

Consider some function  $u(x)$



and suppose it moves at speed  $c$  to the right.

Then now  $u = u(x, t)$  and

$$M = \int_0^b u(x, t) dx = \int_{0+ch}^{b+ch} u(x, t+h) dx$$

Differentiate w.r.t.  $b$  to get

$$\frac{\partial M}{\partial b} = u(b, t) = u(b+ch, t+h)$$

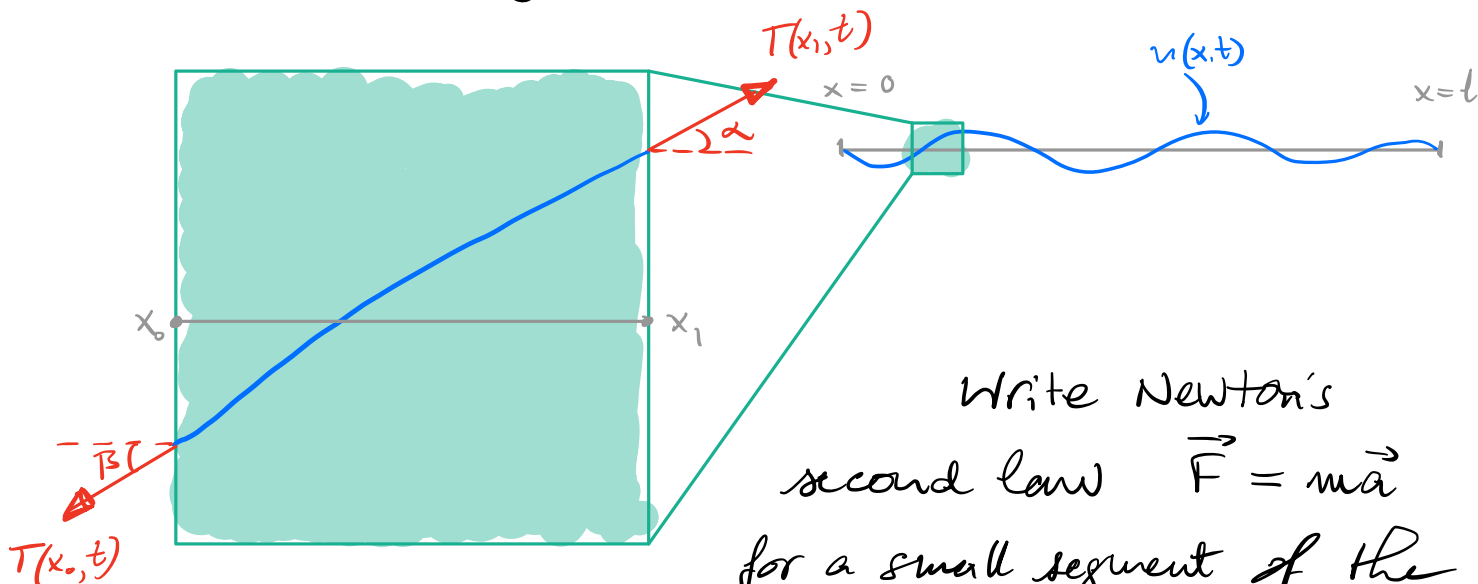
Differentiating this w.r.t.  $h$  we get

$$\begin{aligned} \frac{\partial}{\partial h} \left( \frac{\partial M}{\partial b} \right) &= \frac{\partial}{\partial h} (u(b, t)) = 0 \\ &= \frac{\partial}{\partial h} (u(b+ch, t+h)) = \frac{\partial u}{\partial x} \frac{\partial x}{\partial h} (b+ch) + \frac{\partial u}{\partial t} \frac{\partial t}{\partial h} (t+h) \\ &= u_x(b+ch, t+h) \cdot c + u_t(b+ch, t+h) \cdot 1 \end{aligned}$$

Plugging in  $h=0$  we have:

$$u_t(b, t) + c u_x(b, t) = 0$$

Ex 2: Vibrating string.



Write Newton's second law  $\vec{F} = m\vec{a}$  for a small segment of the string, for horizontal & vertical parts separately.

Horizontal:  $T(x_1, t) \cdot \cos \alpha - T(x_0, t) \cdot \cos \beta = 0$

$$\cos \alpha = \frac{1}{\sqrt{1+u_x^2(x_1, t)}} \approx \frac{1}{1+\frac{1}{2}u_x^2(x_1, t)} \approx 1$$

$$\cos \beta = \frac{1}{\sqrt{1+u_x^2(x_0, t)}} \approx \frac{1}{1+\frac{1}{2}u_x^2(x_0, t)} \approx 1$$

$$\rightarrow T(x_0, t) = T(x_1, t)$$

So  $T$  is independent of  $x$ . We assume that it is also independent of  $t$ .

Vertical:  $T(\sin\alpha - \sin\beta) = F = ma = \int_{x_0}^{x_1} \rho u_{tt}(x, t) dx$

$$\sin\alpha = \frac{u_x(x_1, t)}{\sqrt{1 + u_x^2(x_1, t)}} \approx u_x(x_1, t)$$

$$\sin\beta \approx u_x(x_0, t)$$

$$\rightarrow T(u_x(x_1, t) - u_x(x_0, t)) = \int_{x_0}^{x_1} \rho u_{tt}(x, t) dx$$

Replace  $x_1 = x_0 + h$  and divide by  $h$ :

$$T \frac{u_x(x_0 + h, t) - u_x(x_0, t)}{h} = \frac{1}{h} \int_{x_0}^{x_0 + h} \rho u_{tt}(x, t) dx$$

As  $h \rightarrow 0$  we get:

$$T u_{xx} = \rho u_{tt} \rightarrow u_{tt} = c^2 u_{xx}$$

$c = \sqrt{\frac{T}{\rho}}$

This is the wave equation, and  $c$  turns out to be the wave speed.

In 2D we get

$$u_{tt} = c^2 (u_{xx} + u_{yy})$$

3D

$$u_{tt} = c^2 (u_{xx} + u_{yy} + u_{zz})$$

Theorem: ("Vanishing theorem")

Let open  $D_0 \subset \mathbb{R}^n$   $n \geq 1$ . Let  $f: D_0 \rightarrow \mathbb{R}$  be continuous satisfying  $\iint_D f(\vec{x}) d\vec{x} = 0$  for any open  $D \subset D_0$ .

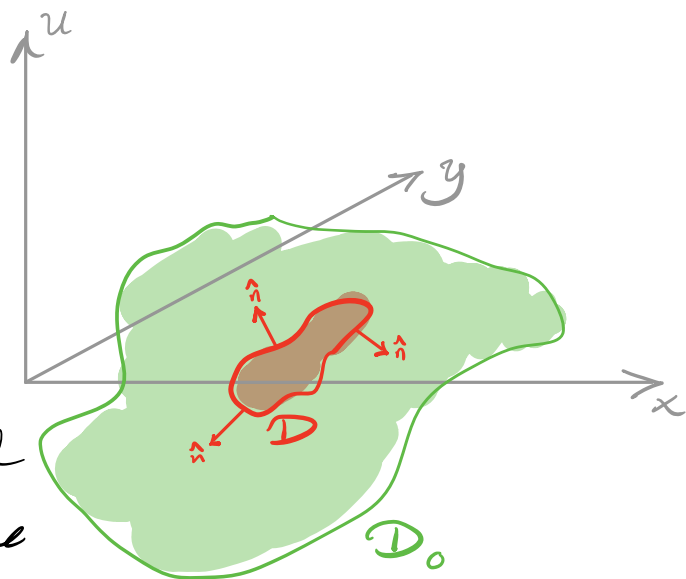
Then  $f$  is identically 0.

Ex 3: Vibrating drumhead.

Let  $D_0 \subset \mathbb{R}^2$  be open.

Suppose that the boundary of  $D_0$  is a frame holding a membrane (like a drum).

Let  $u(x, y, t)$  denote the vertical displacement of the membrane at the point  $(x, y) \in D_0$  at time  $t \in \mathbb{R}$ .



Let  $D \subset D_0$  be any open subset (sometimes called domain). Let  $\vec{T}(x, y, t)$  be the tension, and let  $T(x, y, t) = \|\vec{T}(x, y, t)\|$  (magnitude). As before, the horizontal component guarantees that  $T$  doesn't depend on  $(x, y)$ , and we assume again that it doesn't depend on  $t$ . Similar to the 1D case, the vertical contribution is given by

$$\int_{\partial D} T \frac{\partial u}{\partial n} ds = F = ma = \iint_D \rho u_{tt} dx dy$$

where  $\hat{n}$  is the outward pointing unit normal vector to the boundary of  $D$  and  $\frac{\partial u}{\partial n} = \hat{n} \cdot \nabla u$  is the directional derivative.

By Green's Theorem (which is just the 2D version of the divergence theorem, aka Gauss' Theorem)

$$\iint_D \nabla \cdot (T \nabla u) \, dx \, dy = \iint_D \rho u_{tt} \, dx \, dy$$

equivalently: 
$$\iint_D (\nabla \cdot (T \nabla u) - \rho u_{tt}) \, dx \, dy = 0$$

Since  $D$  is arbitrary, the vanishing theorem implies that

$$\nabla \cdot (T \nabla u) - \rho u_{tt} = 0$$

and since  $T$  is constant we have

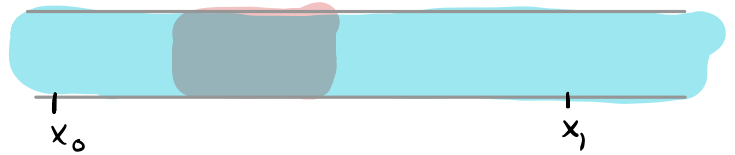
$$u_{tt} = c^2 \nabla \cdot (\nabla u) = c^2 (u_{xx} + u_{yy})$$

where, as before,  $c = \sqrt{\frac{T}{\rho}}$ . In 3D

$$u_{tt} = c^2 (u_{xx} + u_{yy} + u_{zz})$$

We denote  $\Delta u = u_{xx} + u_{yy} + u_{zz}$

## Ex 4: Diffusion.



Fluid in a tube, and dye

diffusing in it. The mass of the dye between  $x_0, x_1$ :

$$M(t) = \int_{x_0}^{x_1} u(x, t) dx \quad (u \text{ is the concentration})$$

$$\frac{dM}{dt} = \int_{x_0}^{x_1} u_t(x, t) dx$$

The mass can only change if dye flows in or out of this section of the tube. So

$$\frac{dM}{dt} = k u_x(x_1, t) - k u_x(x_0, t)$$

( $k$  is a constant that takes care of units)

So we have

$$\int_{x_0}^{x_1} u_t(x, t) dx = k u_x(x_1, t) - k u_x(x_0, t)$$

Again, letting  $x_1 = x_0 + h$  and dividing by  $h$ , we find

$$u_t = k u_{xx}.$$

In 2D we get

$$u_t = k(u_{xx} + u_{yy})$$

3D

$$u_t = k(u_{xx} + u_{yy} + u_{zz})$$

Using the notation  $\Delta = \frac{\partial^2}{\partial x^2} + \dots$  we find  
the general form:

Wave:  $\partial_{tt} u = c^2 \Delta u$

Diffusion:  $\partial_t u = k \Delta u$

Ex 5: Heat flow.

The diffusion eq. also describes heat flow.  
Read this.

Ex 6: Stationary waves and diffusions.

For both the wave eq. and the diffusion eq.  
if the solution doesn't actually depend on time  
then the time derivatives vanish and we're  
left with

$$\Delta u = u_{xx} + u_{yy} + u_{zz} = 0$$

This is called the Laplace eq. Solutions are  
harmonic functions.